MathWorks **AUTOMOTIVE CONFERENCE 2024** Korea

Hardware-in-the-Loop Testing for Battery Management Systems using Speedgoat Test System

Jihun Gong, Inno-X





About *speedgoat*

An associated company of

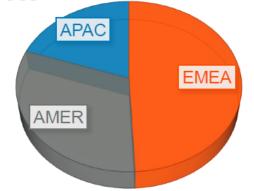


Main offices

- Speedgoat GmbH Switzerland
- Speedgoat GmbH Germany
- Speedgoat Inc USA



Worldwide Sales and Distributor network



Official Speedgoat distributor in Korea





What Do We Offer?

Testing of Control Designs and Embedded Controllers

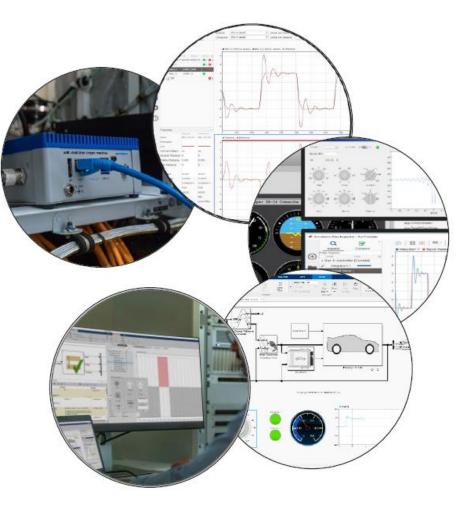
> Virtual & Integrated Testing Solution

- > Deterministic emulation of plants, sensors & actuators
- Plug & play I/O interfacing
- Automate testing
- Comply with certification requirements

Frontload Verification & Validation

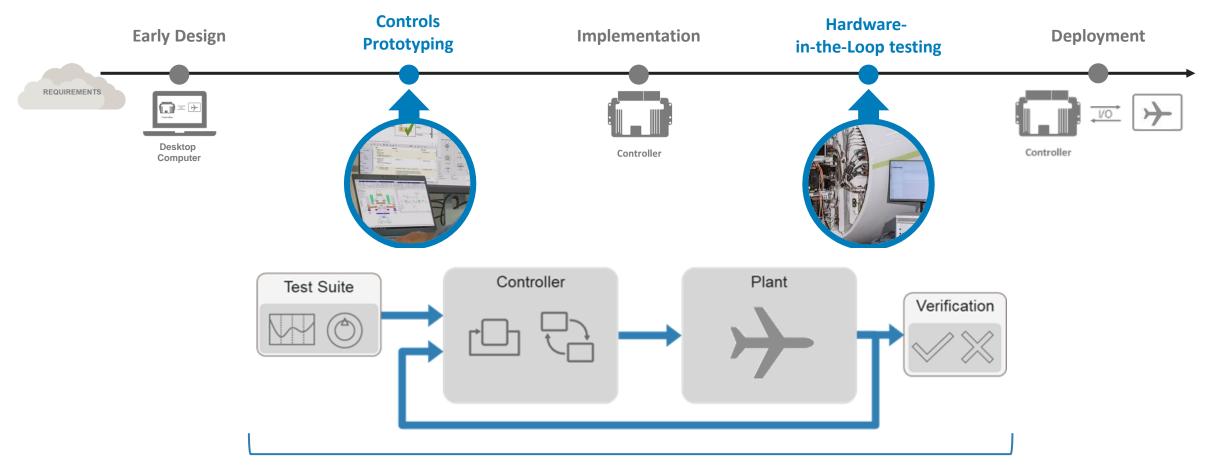
- > Test before plant hardware is available
- Gradually integrate and test plant components
- > Detect design flaws and fix bugs earlier
- Test corner cases and exceedances

speedgoat | 📣 MathWorks[.]



What Do We Offer? Real-Time-Enabled Model-Based Design

speedgoat | 📣 MathWorks[.]



Model-Based Design

What Do We Offer?

Key Value Adds - Unified Desktop and Real-Time Simulation and Testing

Work Better with Tools you Already Know and Trust

- Stay in MATLAB[®] and Simulink[®]
- Deploy and connect to hardware with a few clicks
- Rapidly switch between desktop and real-time simulation
- No extra knowledge required

Partner with an Experienced, Yet Agile, Organization

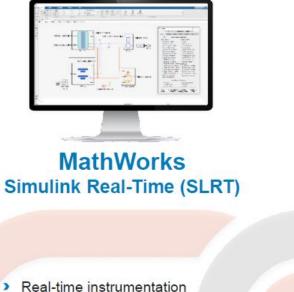
- Two organizations collaborating at all levels
- Synchronized engineering
 - Software/Hardware designed for one another
 - No release version lags
- Unified customer services



Work Better with Tools You Know and Trust

Real-time testing, simplified

- Stay in MATLAB or . Simulink
- Connect to hardware with . a few clicks
- Rapidly switch between . desktop and real-time simulation
- Deploy apps for desktop . or web use



- > Digital Twins
- Automated testing
- Code generation (C/VHDL)





Speedgoat **Real-Time Test Systems**

- > I/O & protocol support
- > FPGA-based solutions
- Speedgoat I/O blockset
- > Complete racks

High-Performance, Scalable, and Modular HIL Test Systems



Performance



Mobile





Baseline

Unit

Multicore Processors

Latest generation Intel CPUs made for hard real-time execution

Choose from 2- to 8-core

Parallel execution and co-execution with FPGAs enabled from Simulink

BlackBerry QNX

On-board connectivity

Gigabit Ethernet ports (UDP, TCP/IP, EtherCAT Master, XCP, PTP 1588)

Serial ports (RS232/422/485)

USB ports

Video ports (HDMI, DVI, VGA or DP)

Low latency / High throughput

PCIe gen 3

Direct Memory Access (DMA)

FPGA based I/O

Flexible I/O & chassis expansion

Add/replace I/O at any time

Expand with I/O expansion units or multi-chassis, distributed simulation

Connectivity and Protocol Support: 200+ I/O Modules

Automotive Protocols

- CAN, CAN FD
- LIN
- FlexRay
- SENT
- PSI5

General Purpose Protocols

- Serial (RS232/RS422/RS485)
- SPI
- I2C
- Ethernet
 - UDP
 - TCP/IP
 - XCP
 - EtherCAT

Motion and Motor Controls

- Low latency analog and digital
- PWM generation and capture
- Encoders (quadrature, SSI, EnDat, BiSS)
- Resolvers
- Cam, Crank

ADAS/AD

- Vision
- Radar
- Lidar

Battery Management Systems

- Cell emulation
- Temperature emulation
- Fault insertion



And more...

- Installed in Speedgoat test system
- Always delivered with Speedgoat I/O blockset, cables, terminal boards, and test models

About Battery Management Systems

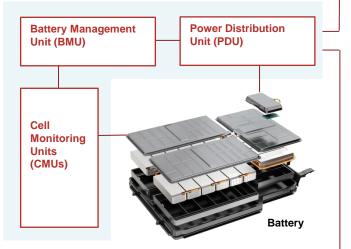
Batteries are crucial for electrification

- Electric Vehicles
- Aircrafts
- Energy storage systems
- Portable devices

Battery Management Systems (BMS) ensure

- Safe operation
- Best performance
- Optimized battery life

Battery Management System













BMS Testing: Challenges with Real Batteries



Batteries age, making it hard to reproduce reliable test conditions to test core algorithms such as:

- Cell balancing
- State of Charge (SoC)
- State of Health (SoH)
- Testing over-voltage, extreme temperature, and fault conditions is dangerous



Batteries, BMS systems, connected products and infrastructures evolve. As a result, there is a need to test a large amount of configurations that can be hardly achieved using real hardware

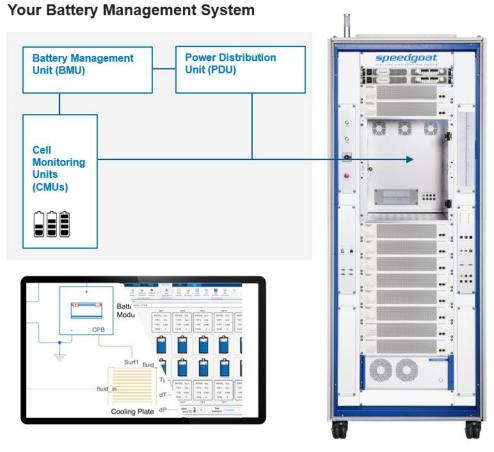




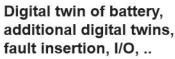
BMS Testing with Digital Twins

Overcome BMS testing challenges with a digital twin of your battery and BMS components

- Flexibly configure different battery pack architectures
- Emulate real voltages and currents
- Adapt as battery technology evolves
- Integrate digital twins for connected components such as motor drives, chargers, and complete powertrains
- Perform requirements-based testing
- Continuously evolve your product and automate testing 24/7



Design and testing software



Automated BMS Testing

1		
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Define battery pack architectures, leverage industry norm specific testing frameworks, and design BMU or CMU algorithms as needed



Define varying battery behavior depending on the battery technology and chemistry, age, surrounding temperatures, and required energies



Emulate battery packs and power distributions at real power levels, and connect the Speedgoat test system to the BMS I/O, protocols and power lines



Perform automated 24/7 testing of your BMS under regular operation and with fault conditions

Battery Management Power Distribution speedqoa Unit (PDU) Unit (BMU) Cell Monitoring Units (CMUs)

Design and testing software

Your Battery Management System

Digital twin of battery, additional digital twins, fault insertion, I/O, ..

Key Components of the Speedgoat and MathWorks[®] Solution

Ready to Use Battery Pack Architectures, CMU and BMU algorithmic designs

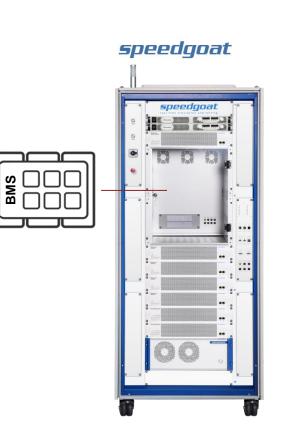
 Leverage and adopt ready to use Simulink reference designs to your needs

Complete Battery Pack Emulation

- Cell emulation at real voltage and power levels
- Power distribution emulation
- Temperature emulation
- Fault insertion support
- Communication protocols

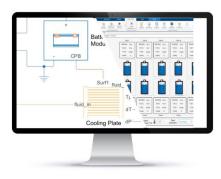
Requirements-based Test Automation

- Define requirements, and run tests 24/7
- Expand testing by also emulating motor drives, fuel cells or charging components



BMS test system Emulate up to 252 cells



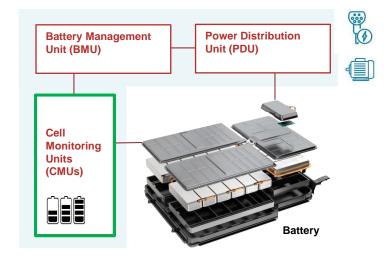


MATLAB[®] & Simulink[®]

- Design CMU and BMU algorithms
- Define battery pack architecture
- Interface with the Speedgoat BMS test system
- Perform automated, requirements based testing

Test Cell Monitoring Units

- Cell balancing, charging, and discharging algorithms
- Test against actual voltage, power, and temperature levels
- Test safely up to 1.3 kV
- Test behavior with faulty cells or overvoltage without risk
- Test with partially emulated CMUs connected through isolated protocols
- Test communication to and from BMU through isolated protocols

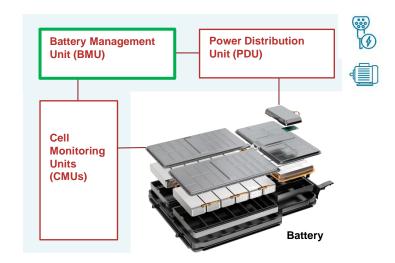


- Cell voltage measurement
- Cell current balancing
- Battery pack temperature monitoring

Test the Battery Management Unit

- Test algorithms such as protection, state of charge (SoC) and state of health (SoH)
- Test with real connectivity to and from Power Distribution with emulated sensors (e.g. shunt sensor, pyro fuse), high voltage measurements, or contactors
- Test communication to CMU, Power Distribution, or Vehicle Control Unit (VCU) through isolated protocols
- Test BMU behavior in case of a collision or other extreme events

- Data exchange between CMU and PDU
- Algorithms: State of charge (SoC), state of health (SoC), ...



Test the Power Distribution Unit

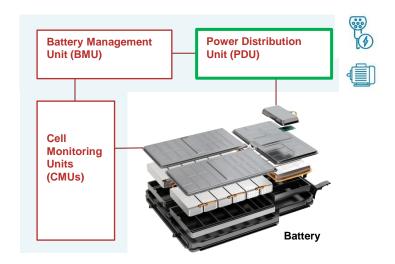
Test power distribution and protocols interfaces from the battery pack to:

- charging components
- motor drives
- fuel cells
- other components leveraging battery power

Test electrical systems and safety components like:

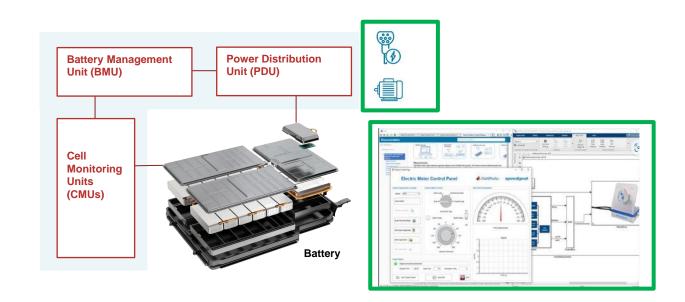
- high voltage and shunt sensors
- current sensors
- contactors
- pyro fuses

- PDU also known as junction, fuse or switch box
- Test power and communication lines
- Test safety conditions



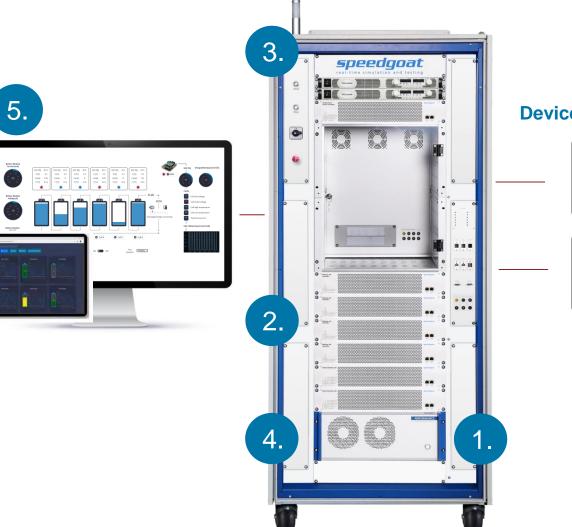
Simulate and Test Interfaced Components

- Motors and drives
- Fuel cells
- Onboard charger or charging station
- Power electronics like DC/DC converters
- Complete powertrains
- Complete vehicles or aircrafts
- Other batteries
- and more!

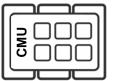


A Scalable BMS Test System

- 1. Real-time target machine with I/O and protocols
- 2. Battery cell and temperature sensor emulators, and fault insertion units
- 3. Scalable rack design
- 4. Power distribution emulation
- 5. Software: Define battery pack topology, design algorithms, configure power and I/O lines, and perform requirements-based testing



Devices under Test:



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1. Real-time target machine with I/O and Protocols

Select from a range of over 200 I/O modules, and benefit from a seamless Simulink integration

Built for High-Performance

- Performance real-time target machine with multicore CPU and programmable FPGAs
- Made for use with Simulink and Simulink Real-Time[™]

I/O and Protocols Interfaces

- Bus and isolated protocols (SPI, CAN, UART,...)
- Shunt emulation
- Cell controller emulation
- Fault insertion







Cell-level emulation and measurement

- Replicate dynamic behavior of various battery types
- 12 independent and isolated battery cells
- Different voltage options: 5V, 6V or 8V
- Sink and source current up to 5A

Power input and interlock

- 48 VDC voltage input, rated 10 A
- Global enable for all cells

Test small BMS components and large battery packs

 Rack integration for large HIL testing or as standalone for testing individual BMS components

Battery Cell Emulators (BCE)

Test and validate your BMS

- Source and Sink capabilities
- Precise voltage and current measurements

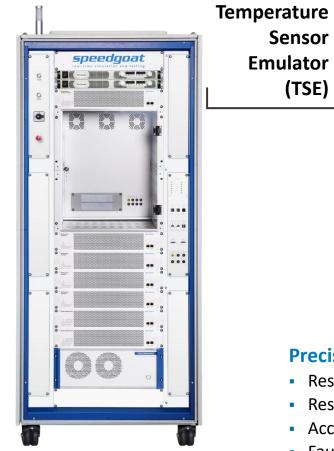
ALLER & B. B. B. B. B.

 Test and validate BMS such as SoC, SoH or cell balancing

Reproduce battery packs

- Stackable design Stack up to 252 cells @5V
- Series connections
- High cell-to-ground isolation: 1.3kV

2. Temperature Sensor Emulator



High-Precision and Isolated Temperature Emulation

 Emulate temperature sensors, such as PTC and NTC, for BMS thermal management



Compact and scalable

- 4 up to 36 channels on one 2U unit
- Multiple units per rack



Precise Temperature Profiles

- Resistance Range: 10Ω to $4M\Omega$
- Resolution: 1Ω
- Accuracy ±0.1% ± 500mΩ
- Fault Insertion: open and short circuit (typically 50mΩ)

Power input and interlock

- 48 VDC voltage input, rated 3 A
- Global enable for all cells

2. Fault Insertion Unit



Extend battery cell emulation with failure insertion capabilities



Compact and scalable

- 12 up to 36 channels on one 2U unit
- Multiple units per rack

Fault Insertion Units (FIU)

Test and validate BMS in normal and fault conditions

Fault scenarios:

- Short-circuit
- Battery-cell broken-wire
- Reverse polarity
- BMS sense line broken-wire

Power input and interlock

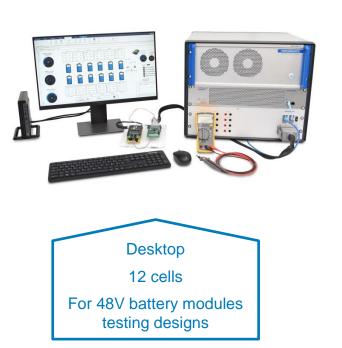
- 48 VDC voltage input, rated 3 A
- Global enable for all cells

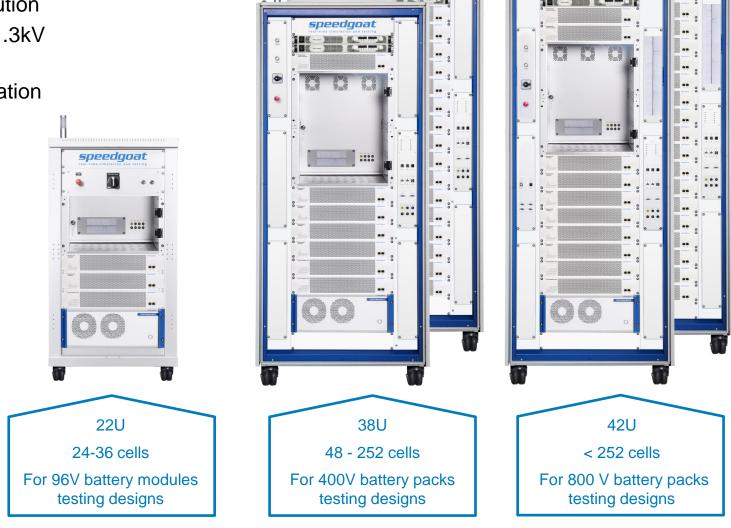
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3. BMS Test System Scalability

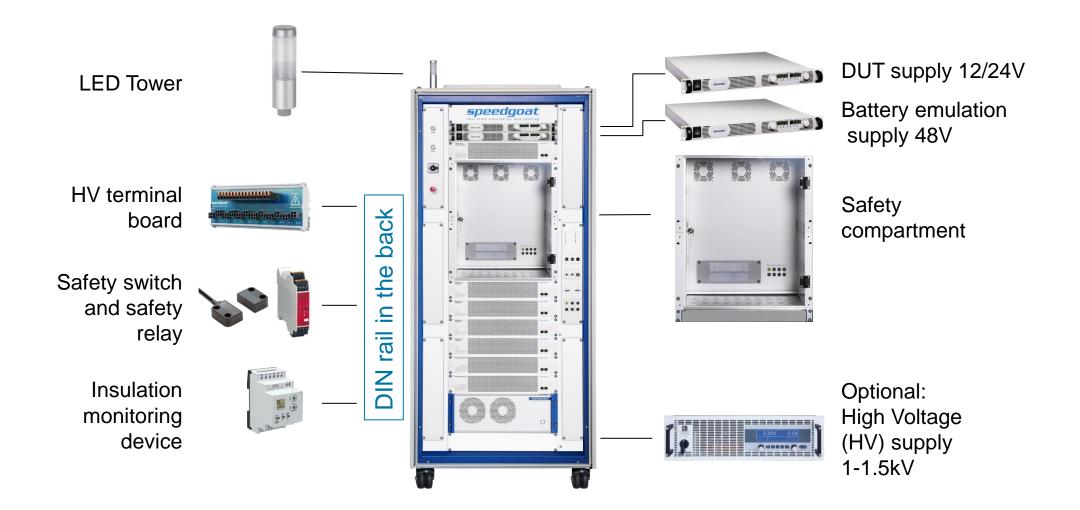
- 22U, 38U or 42U rack or desktop solution
- Emulate up to 252 battery cells with 1.3kV cell-to-ground isolation
- Include temperature and power emulation
- Add I/O and protocol interfaces



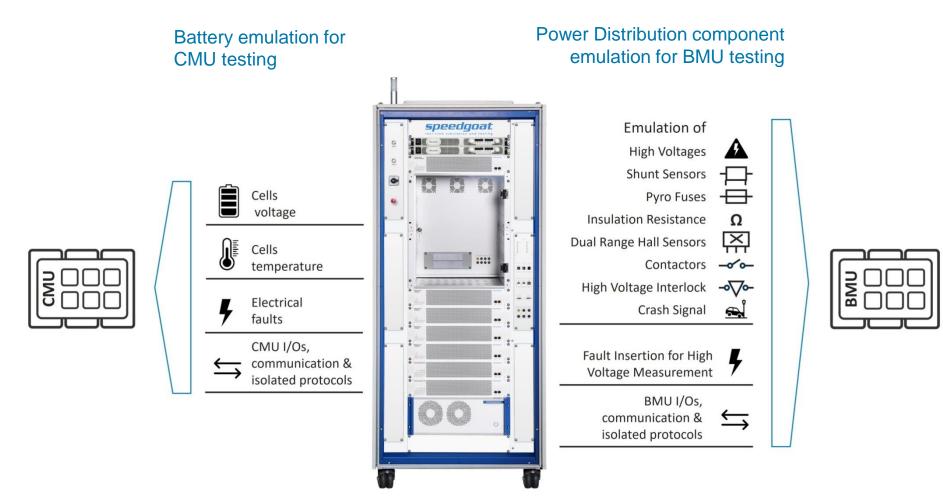


speedgoat



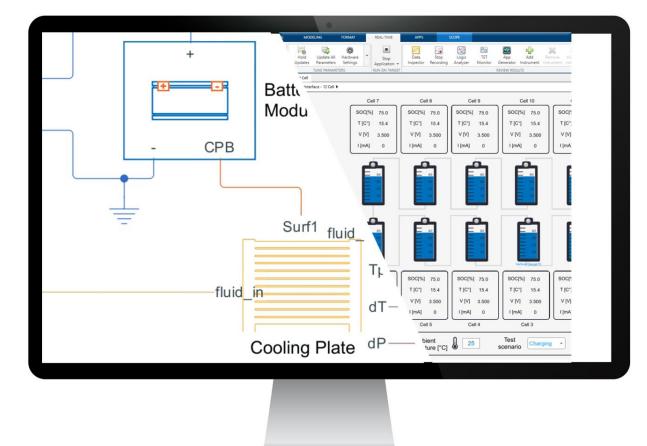


4. Emulation of Power Distribution Components



5. Battery Pack Architecture Definition

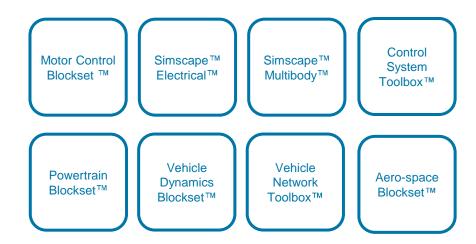
- Leverage reference example, and adjust to your needs with Simulink and Simscape[™] Battery[™]
- Monitor and instrument from a Simulink dashboard, or using AppDesigner
 - Inspect SoC, temperature and voltage of cells
 - Monitor balancing currents



5. Expand Testing to Additional Components

Leverage Speedgoat Test Systems to test control designs and controllers for:

- Motors drives
- Fuel cells
- Charging
- Power electronics
- Complete powertrains
- Complete vehicles or aircrafts
- and more!



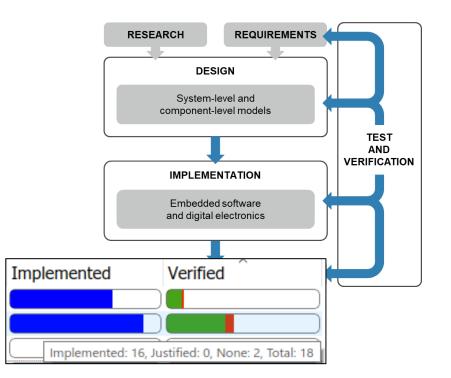
Examples of a few Simulink Blockset libraries

5. Perform Requirements-based Testing

Leverage the Requirements Toolbox to:

- Author or import, link and validate requirements
- Trace and document verified results with requirements
- Identify gaps in design or test
- Respond flexibly to requirements changes

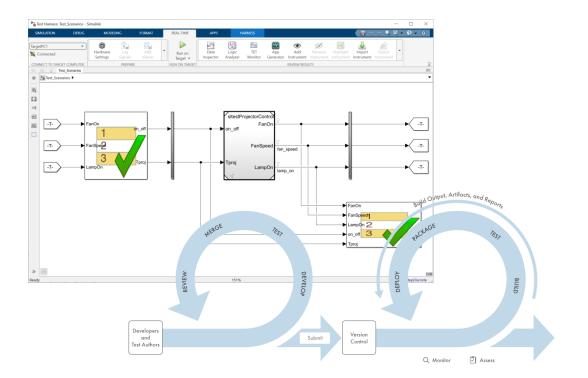
Learn more: <u>Requirements Toolbox - MATLAB</u>



5. Automate Requirements-based Testing

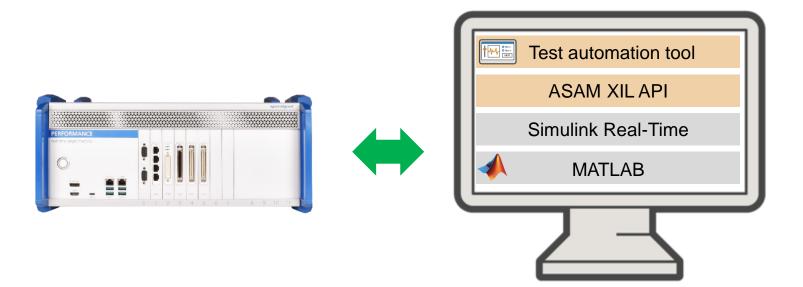
Enable continuous integration and testing through test automation

- Create test suites
- Automate and reuse
- Use Simulink Test™, Test Manager, or MATLAB scripts

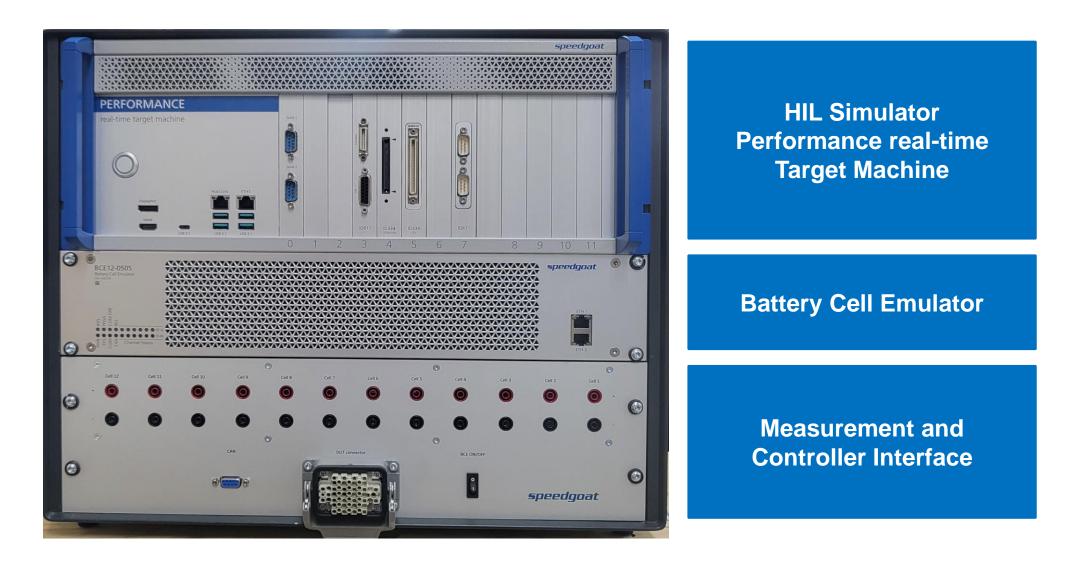


Learn more: <u>Test Real-Time Application in Simulink Test</u> Projector Controller Testing Using verify and Real-Time Tests

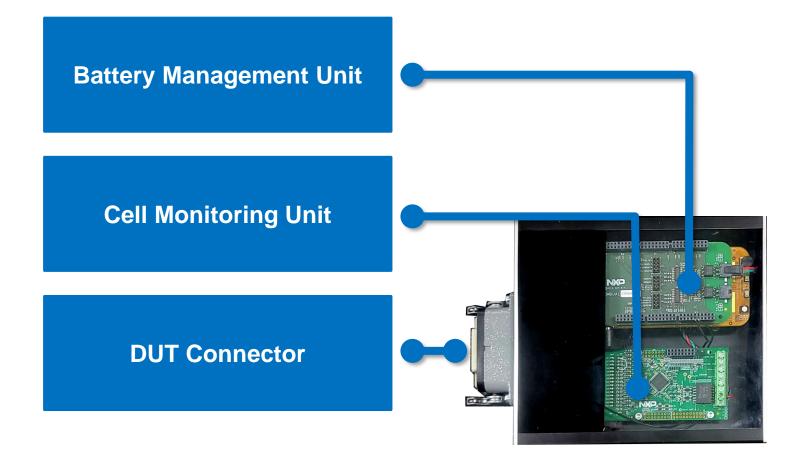
5. Connect with third-party test platforms through ASAM XIL



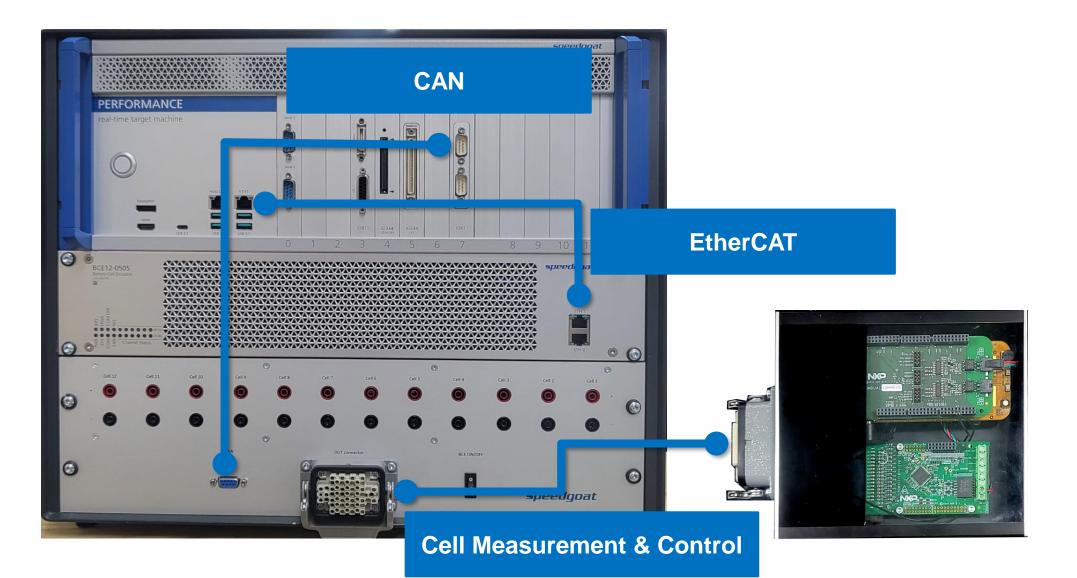
BMS HIL Testing Demo – Components



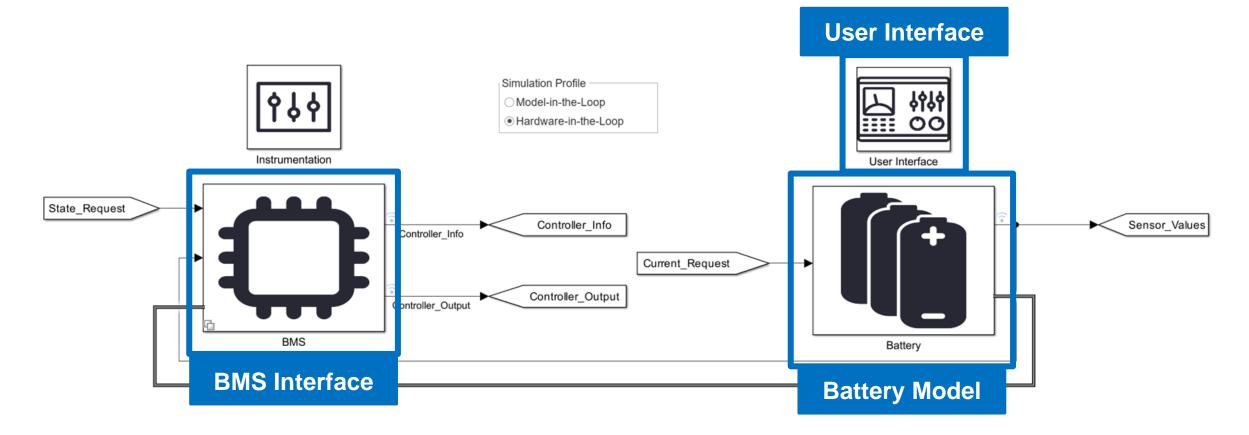
BMS HIL Testing Demo – Components



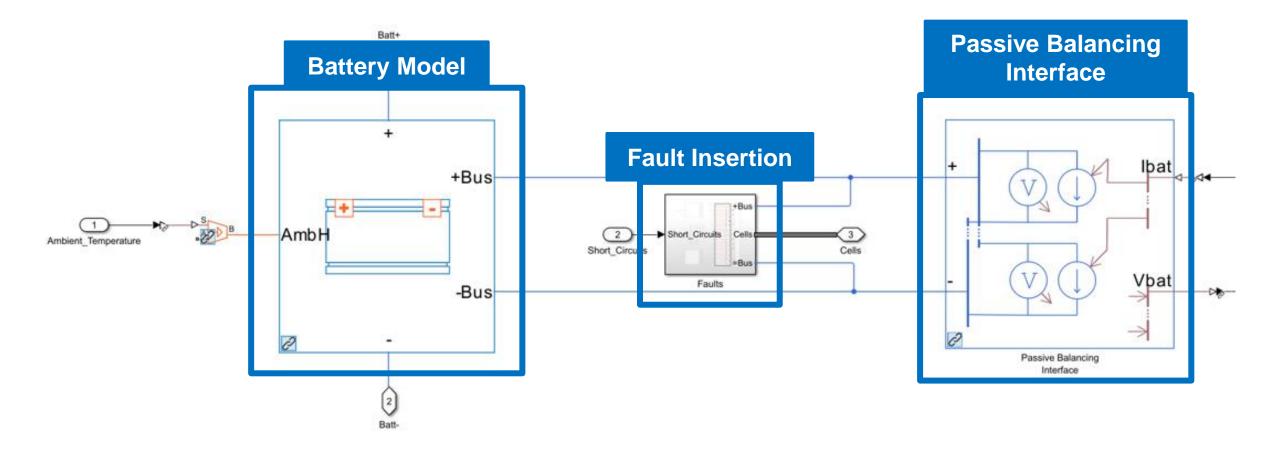
BMS HIL Testing Demo – Interface



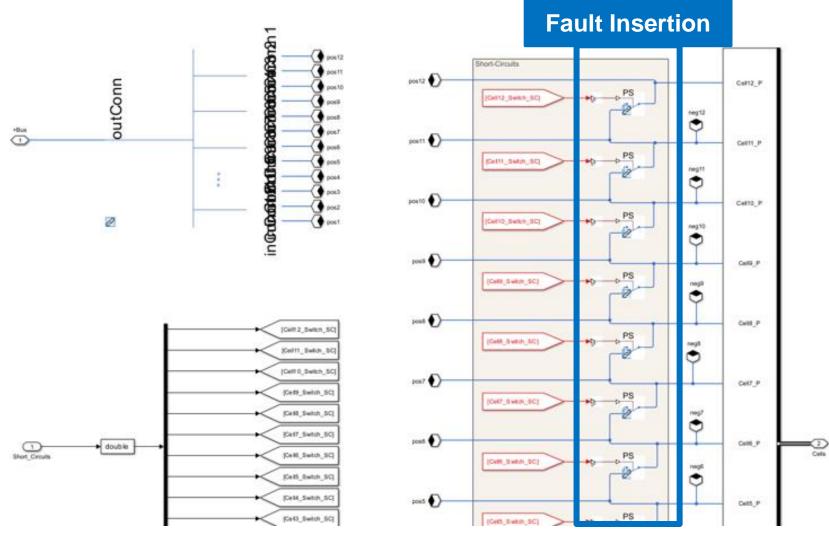
- Battery Model
- Interface to DUT
- User Interface



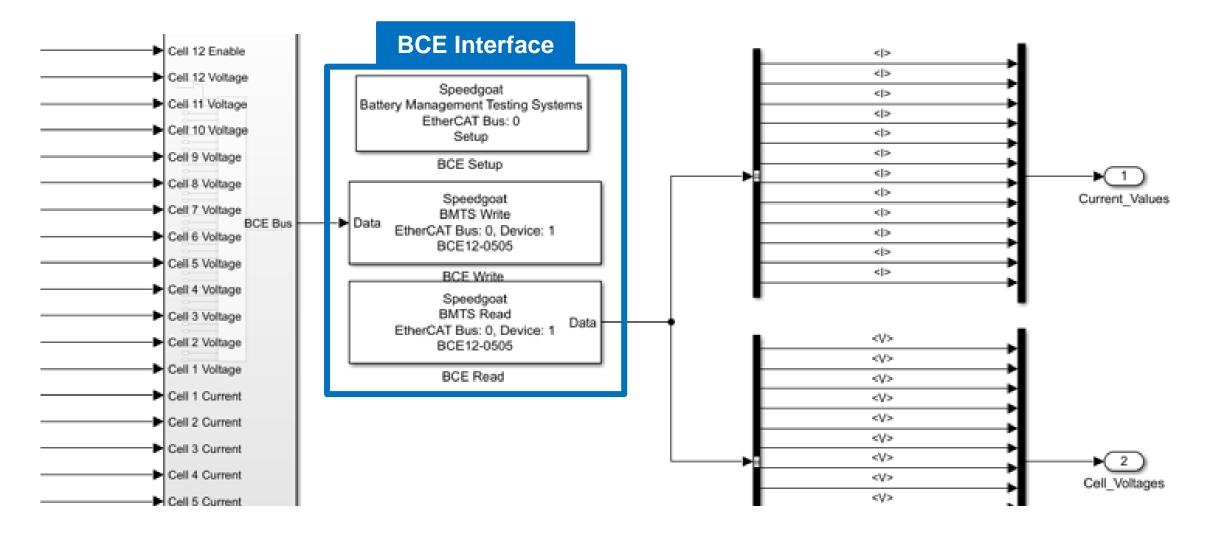
Battery Model using Simscape



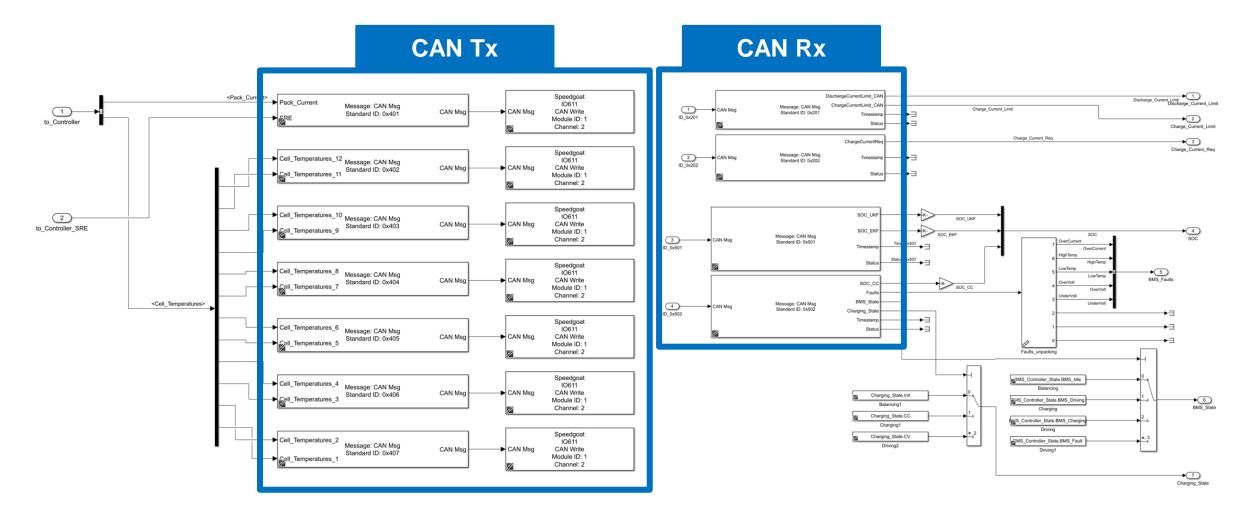
Fault Insertion using Switch



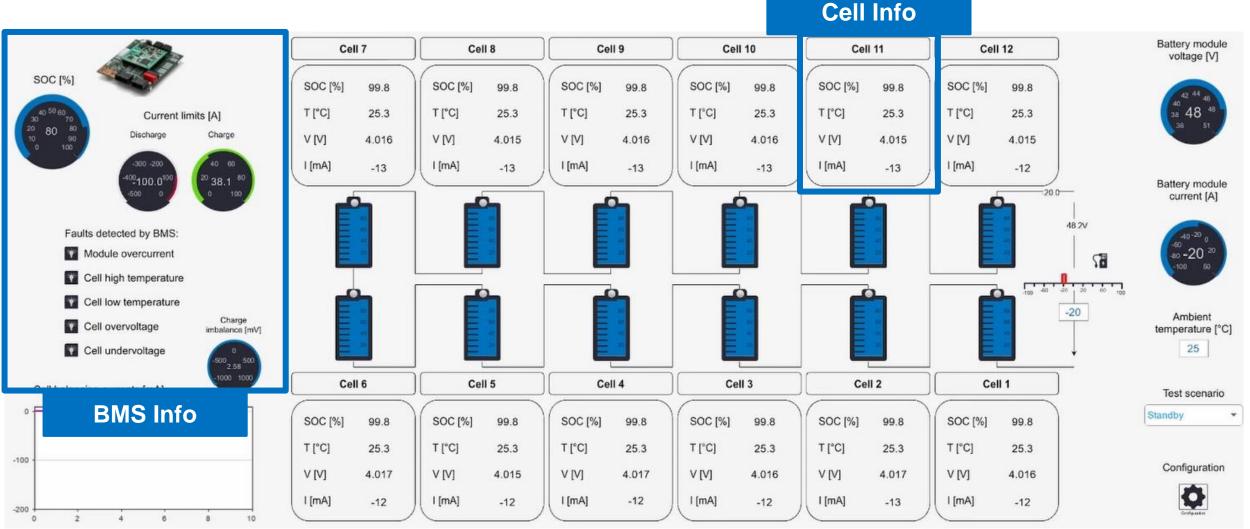
Interface to Battery Cell Emulator using Speedgoat Library



CAN Interface to BMS



User Interface



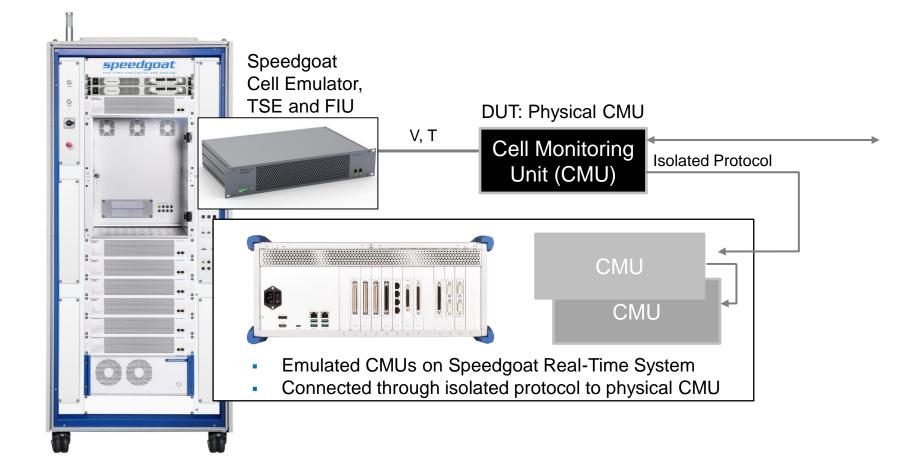
Cell Configuration **Cell Override** Cell 7 Cell 8 Cell 9 Cell 10 Cell 11 Cell 12 Overrides Overrides Overrides Overrides Overrides Overrides or 💽 on V [V] or on V [V] or 💽 on V [V] 4 4 4 4 4 or 🕥 or T [°C] 🗟 25 ● T [°C] 25 or 🗩 on T [°C] 25 or 🗩 on T [°C] 25 **Fault Insertion** Fault Insertion Fault Insertion Fault Insertion Fault Insertion Fault Insertion Fault Insertion or Don Short-Ciruit or O Short-Ciruit or Short-Ciruit or 🗩 🗠 Short-Ciruit or Short-Ciruit or 🔵 🗠 Short-Ciruit or Don Broken-Wire or Don Broken-Wire or Don Broken-Wire or Do Broken-Wire or m Broken-Wire or Do Broken-Wire Cell 6 Cell 5 Cell 4 Cell 3 Cell 2 Cell 1 Overrides Overrides Overrides Overrides Overrides Overrides or 💽 on V [V] 4 4 4 4 or on V [V] 4 or 💽 on V [V] 4 or ◯ つ T [°C] or ◯ つ T [°C] or 🗩 or t [°C] 25 25 25 ∝ 🗩 ∾ T [°C] 25 on T [°C] 25 Fault Insertion Fault Insertion Fault Insertion Fault Insertion Fault Insertion Fault Insertion or n Short-Ciruit or Short-Ciruit or Short-Ciruit or 🕥 on Short-Ciruit or O Short-Ciruit or n Short-Ciruit or Don Broken-Wire or D on Broken-Wire or 🗩 on Broken-Wire or Don Broken-Wire or n Broken-Wire or Don Broken-Wire

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ULATION DEBUG	MODELING FORMAT	REAL-TIME A	NPPS					୦ ୯ 🍳 ଅ. ବ 🕐 🔹
	Hardware Target Log Settings Platform Signals PREPARE Instrumentation × Battery Cell E	Run on Target • RUN ON TARGET	ta Stop Logic	TET Import File App Monitor Log Generat REVIEW RESULTS		lighlight strument		
🔊 System 🕨 🎦 User Inter	face 🕨							
		A						
		Cell 7	Cell 8	Cell 9	Cell 10	Cell 11	Cell 12	Battery modul voltage [V]
SOC [%]		SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	42 44 46 40 4 0 48
30 ¹ 70 20 80 80 10 90 0 100	Current limits [A] Discharge Charge	T [°C] 28.4 V [V] 4.007	T [°C] 28.4 V [V] 4.008	T [°C] 28.4 V [V] 4.009	T [°C] 28.4 V [V] 4.008	T [°C] 28.4 V [V] 4.009	T [°C] 28.4 V [V] 4.008	38 48 ⁴⁸ 36 51
	-300 -200 -400-100.0 ¹⁰⁰ -500 0 -500 0 -500	I[mA] -13	I [mA] -13	I [mA] -12	I [mA] -13	I [mA] -12	I [mA] -12	Battery modul current [A]
	atected by BMS: ule overcurrent		2 9 9 9 F		80 80 40 70			40 ⁻²⁰ 0 -60 -80 -20 20 -100 50
	high temperature low temperature							
the second second	overvoltage Charge imbalance [mV] undervoltage 0 500 3.28 500		40		100 100 211			Ambient temperature [° 25
Cell balancing of	-1000 1000	Cell 6	Cell 5	Cell 4	Cell 3	Cell 2	Cell 1	Test scenario
0		SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	SOC [%] 99.2	Standby
-100 -		T [°C] 28.4	T [°C] 28.4	T [°C] 28.4	T [°C] 28.4	T [°C] 28.4	T [°C] 28.4	0
		V [V] 4.008	V [V] 4.008	V [V] 4.009	V [V] 4.007	V [V] 4.010	V [V] 4.008	Configuration
-200 22 22	24 28 28 30	<u> </u>	<u>Л</u>					Configuration

Read

BMS HIL Testing CMU Testing with Partially Emulated CMUs



BMS HIL Testing Reference Application

Demo: Hardware-in-the-Loop Testing of Battery Management Systems

- Download ready-to-use Simulink models from the Speedgoat website
- Access with log-in



Learn How to

- Model a 48V battery system using Simscape Electrical
- Go from model-in-the-loop (MIL) to hardware-in-the-loop without leaving Simulink or changing your model
- Interface your Simulink/Simscape battery models with battery cell
 emulation hardware
- Validate BMS functions, such as fault detection, cell balancing, and state of charge estimation
- Implement bus and signal-level communication with the BMS controller
- · Simulate temperature sensors and implement fault conditions



Use Case Example: Leclanché

Next-Gen Li-Ion Battery Packs for Autonomous Vehicles

Challenge

- Unable to test and verify Battery Management Systems in realistic operating conditions before connecting to actual battery packs
- Late bug discovery and no preliminary testing can damage batteries
- Poor development tool compatibility leading to manual testing

Solution

- Use Simulink and Speedgoat products for HIL testing of BMS
- Speedgoat test platform with cell emulators, fault insertion, and CAN communication
- Simulink Test[™] to thoroughly validate BMS and battery state estimation algorithms (SoC, SoH, etc.)

Results

- Reduced testing time by 50%
- Increased test coverage for safety features by 40%
- Faster development with early bug detection

See more Success Stories https://www.speedgoat.com/success-stories

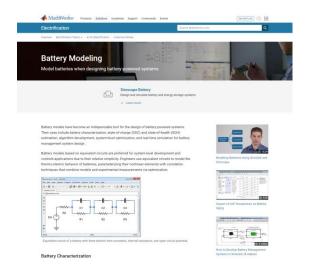




"Speedgoat and MathWorks products together offer a very efficient workflow to design, test and validate Battery Management Systems"

Marc Lucea, Senior Application SW Engineer

Additional Resources

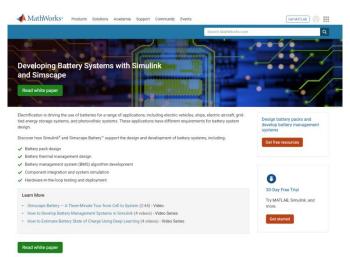


Websites

Battery Management Systems Testing -Battery Cell Emulator

Battery Modeling - MATLAB & Simulink

Battery Systems - MATLAB & Simulink



Whitepaper

Developing Battery Systems with Simulink and Simscape - MATLAB & Simulink



Webinars and Videos Hardware-in-the-Loop Testing of Battery Management Systems | Speedgoat

Real-Time Testing for VTOL and Conventional Aircraft Development | Speedgoat

Enabling Innovation for Automotive Hardware-inthe-Loop Testing and Control Design | Speedgoat

Optimize EV Battery Performance Using Simulation Video - MATLAB & Simulink

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